

We are unable to supply this entire article because the publisher requires payment of a copyright fee. You may be able to obtain a copy from your local library, or from various commercial document delivery services.

From Forest Nursery Notes, Winter 2012

**129. © Development of a walk-behind type hand tractor powered vegetable transplanter for paper pot seedlings.** Kumar, G. V. P. and Raheman, H. Biosystems Engineering 110:189-197. 2011.

Available at [www.sciencedirect.com](http://www.sciencedirect.com)journal homepage: [www.elsevier.com/locate/issn/15375110](http://www.elsevier.com/locate/issn/15375110)

## Research Paper

# Development of a walk-behind type hand tractor powered vegetable transplanter for paper pot seedlings

G.V. Prasanna Kumar<sup>a,\*</sup>, H. Raheman<sup>b</sup>

<sup>a</sup>Department of Agricultural Engineering, North Eastern Regional Institute of Science and Technology, Nirjuli 791109, Itanagar, Arunachal Pradesh, India

<sup>b</sup>Agricultural and Food Engineering Department, Indian Institute of Technology, Kharagpur 721302, West Bengal, India

### ARTICLE INFO

#### Article history:

Received 1 May 2011

Received in revised form

17 July 2011

Accepted 1 August 2011

Published online 30 August 2011

A 9.75 kW walk-behind type hand tractor powered 2-row fully automatic vegetable transplanter for individual paper pot seedlings was developed by considering the power availability, paper pot dimensions and space availability in the hand tractor after the complete removal of rotavator tillage assembly. It consisted of two sets of feeding conveyor, metering conveyor, seedling drop tube, furrow opener, soil covering device, an automatic feeding mechanism, a depth adjustment wheel and hitching arrangement. Horizontal slat-type chain conveyor was used as feeding conveyor and horizontal pusher type chain conveyor was used as metering conveyor. The automatic feeding mechanism, with a timing shaft, cam and clutch, was used to coordinate the working of feeding and metering conveyors. The vegetable transplanter carried 108 seedlings on two feeding conveyors in upright orientation, fed them to the metering conveyors and planted them in upright orientation in furrows. The performance of the vegetable transplanter was evaluated for transplanting tomato at  $45 \times 45$  cm spacing in the field at a forward speed of  $0.9 \text{ km h}^{-1}$ . Field capacity of the transplanter was found to be  $0.026 \text{ ha h}^{-1}$ . It resulted in the saving of 68% labour and 80% time over the conventional method of manual transplanting. The planting rate of the transplanter was found to be 32 pot seedlings  $\text{min}^{-1}$  with 4% missed planting and 5% tilted planting. The soil covering efficiency of the developed vegetable transplanter was about 81% and the quality of transplanting was satisfactory.

© 2011 IAGrE. Published by Elsevier Ltd. All rights reserved.

## 1. Introduction

India is the second largest producer of vegetables with the production of 129 million metric tons and yield of 16.2 metric tons  $\text{ha}^{-1}$  in the year 2008–2009 (Government of India, 2009). About 175 types of vegetables are grown in India including 82 field vegetables and 41 root (tuber and bulb) crops (Randhawa, 1998; Subramanian, Varadarajan, & Asokan, 2000). Most of the

vegetables like cucurbits (*Cucurbita* spp.), beans (*Phaseolus* spp.), okra (*Abelmoschus esculentus*) and leafy vegetables are sown directly in the field. Vegetables like tomato (*Solanum lycopersicum*), eggplant (*Solanum melongena*) and peppers (*Capsicum* spp.) are first sown in nursery beds and later transplanted manually either on ridges or on a well prepared seedbed (Ghai & Arora, 2007). Manual transplanting of seedlings is labour-intensive, expensive, time consuming and

\* Corresponding author. Tel.: +91 360 2257379; fax: +91 360 2258533/2257872.

E-mail address: [gvpk@yahoo.com](mailto:gvpk@yahoo.com) (G.V.P. Kumar).

1537-5110/\$ – see front matter © 2011 IAGrE. Published by Elsevier Ltd. All rights reserved.

doi:10.1016/j.biosystemseng.2011.08.001